# Inductance (units)

- Inductor is a device used to produce and store a desired *B* field (e.g. solenoid)
- A current, *i*, in an inductor with *N* turns produces a magnetic flux,  $\Phi_{\rm B}$ , in its central region
- Inductance, *L* is defined as

$$L = \frac{N\Phi_B}{i}$$

SI unit is henry, H

$$H = T \cdot m^2 / A$$

# Inductance of a solenoid

 $L = \frac{N\Phi_B}{M}$ 

- What is inductance of a solenoid?
- First find flux of single loop in solenoid

$$\Phi_B = \int \vec{B} \bullet d\vec{A} = BA = \mu_0 niA$$

• # of turns (N) per unit length (/) n = N / l

• Thus 
$$L = l\mu_0 n^2 A$$
 or  $\frac{L}{l} = \mu_0 n^2$ .

 Depends only on the physical properties of the solenoid

- Generators convert mechanical energy to electrical energy
- External agent rotates
  loop of wire in *B* field
  - Hydroelectric plant
  - Coal burning plant
- Changing Φ<sub>B</sub> induces an emf and current in an external circuit



#### Alternating current (ac) generator

- Ends of wire loop are attached to slip rings which rotate with loop
- Stationary metal brushes are in contact with slip rings and connected to external circuit
- emf and current in circuit alternate in time



- Calculate emf for generator with N turns of area A and rotating with constant angular velocity, ω
- Magnetic flux is

$$\Phi_B = \int \vec{B} \bullet d\vec{A} = BA\cos\theta$$

 Relate angular displacement to angular velocity

$$\theta = \omega t$$



 Flux through one loop is

$$\Phi_B = BA\cos\omega t$$

• Faraday's law says



Substitute

 $\Phi_{B} = BA\cos\omega t$ 

$$\mathcal{E} = -NBA \frac{d}{dt} (\cos \omega t)$$

$$\mathcal{E} = NBA\omega\sin\omega t$$

• Maximum emf is when  $\omega t = 90$  or 270 degrees

$$\mathcal{E}_{\max} = NBA \omega$$

 Emf is 0 when ωt = 0 or 180 degrees



#### Direct current (dc) generator

- Ends of loop are connected to a single split ring
- Metal brush contacts to split ring reverse their roles every half cycle
- Polarity of induced emf reverses but polarity of split ring remains the same



- Not suitable for most applications
  - Can use to charge batteries
- Commercial dc gen.
  use out of phase coils

### Motors

- Motors converts electrical energy to mechanical energy
  - Generator run in reverse
  - Current is supplied to loop and the torque acting on the current-carrying loop causes it to rotate
  - Do mechanical work by using the rotating armature
  - As loop rotates, changing *B* field induces an emf
  - Induced emf (back emf) reduces the current in the loop – remember Lenz's law
  - Power requirements are greater for starting a motor and for running it under heavy loads

## Self-induction

- A changing current in a coil generates a self-induced emf,
   ε<sub>L</sub> in the coil
- Process is called self-induction
- Change current in coil using a variable resistor, ε<sub>L</sub> will appear in coil only while the current is changing





$$\mathcal{E}_{L} = -N\frac{d\Phi_{B}}{dt} = -\frac{d(N\Phi_{B})}{dt} = -\frac{d(Li)}{dt} = -L\frac{di}{dt}$$

# Self-induction

- Induced emf only depends on rate of change of current, not its magnitude
- Direction of ε<sub>L</sub> follows Lenz's law and opposes the change in current
- Self-induced V<sub>L</sub> across inductor
  - Ideal inductor
- $V_L = \mathcal{E}_L$ 
  - Real inductor (like real battery) has some internal resistance

$$V_L = \mathcal{E}_L - iR$$







#### Exercise

 Have an induced emf in a coil. What can we tell about the current through the coil? Is it moving right or left and is it constant, decreasing or increasing?



Only get  $\mathbf{E}_{L}$  if current changing

Decreasing and rightward OR Increasing and leftward